# Communication aspects of multi-agent unmanned systems

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#### Mostofi's Research Lab

- Using multiple robots to map environment, including hidden obstacles
- Achieved with lasers and wireless networks





Measuring the drop in signal strength



# Path during experiment



#### Mostofi's Research Lab

- These capabilities can be used for:
  - Emergency Response
  - Surveillance and Security
  - o Defense
  - Intelligent homes and factories
  - Environmental Monitoring

#### Goals

- Simulating communication transceivers
- Effects of channel
  - o Noise
  - o Multipath
- Design a replica of mounting fixture of antenna

# Simulation of Signal Transmission





#### Convolution



### Convolution







### In reality, transmitters and receivers are not always perfectly synced



Example: Transmitter has a phase shift and frequency offset

The transmitter is not in sync with the Receiver



Here, input is sinusoidal

Signals are not in phase, and they vary at slightly different frequencies Without an offset the Bit Error from transmitter to receiver was 0%

With a phase shift pi/2 and frequency offset 1/25T the Bit Error from transmitter to receiver was 49%

## Channel noise



 $\mathbf{y}(t) = \mathbf{x}(t) + \mathbf{n}(t)$ 

x(t) is the signal

n(t) is the noise

SNR = x(t)/n(t)



Multiple version of same signal are sent



Summary of Project

- Developed expertise in MatLab, and signal processing
- Contributed to the lab by designing the antenna fixture in AutoCad

### Antenna fixture model





## Future work

• Still working on the simulation to reduce noise in the signal.

• Will be fabricating the model

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INSET

#### Thank You!



### Matched filters

This is from convoluting the transmit and receive filter, Raise Cosine filter



## Signal after a multi channel path



A multiple path channel filter, which creates noise. Currently working on reducing the noise created by ISI.